TECNORD STANDARD PRODUCT LINE

Mod. IP-PRZ-T059 "Zero Off-Set" Proportional Pressure Reducing Valve

Pressure Reducing Valves

IP-PRZ (Slip-in version) and EG-TRZ (Threaded version) are pilot-operated pressurereducing valves used to generate a variable pressure in response to a PWM (Pulse width Modulated)current signal .

APPLICATIONS

- Micro-processor controlled power shift transmissions for off-higway equipment, agricultural tractors and marine inverters
- · Electro-hydraulic proportional control of directional valves amd variable displacement pumps servo-valves
- · Electro-hydraulic proportional strokers for Engine Speed Governors







Press (bar) vs. Current (mA) Curve with 1.

> quick fill-up phase followed by a modulation ramp

Typical Clutch Cycle: 2.

> - Preliminary "quick fill-up" phase at top current until pressure begins to raise within the cluctch piston chamber

- Modulated Current ramp to generate a "soft engagement" of clucth discs





PRINCIPLE OF OPERATION

QUICK FILL-UP: a high current peak fed to the propotional solenoid of the IP-PRZ-59, generates a quick shifting of the valve spool and to fill up the interstices between clutch disc in the shortest possible time. Clutch discs enter in touch with each other to begin to transfer torque and speed (= power) from the INPUT to the OUTPUT shaft

SOFT ENGAGEMENT: thePWM current signal is quickly reduced to a minimum value in order to ler the pressure start from a "low end" (2 bar) and then ramped up smoothly to a "high end" (16-18 bar) during which the torque is gradually transmitted to the friven shaft.



TRANSMISSION VALVES

TECNORD FIELD OF EXPERTISE:

Electro-Hydraulic Valve System for:



AGRICULTURAL TRACTORS



BRAKE & STEERING MANIFOLD VALVE

POWERSHIFT VALVE SYSTEM









ENGINE RPM PROPORTIONAL STROKER

IN-CABIN CONTROLS



XUANGONG DOZER Mod. SD7





CRAWLER DOZERS

XUANGONG DOZER Mod. SD7 in action



P/N 15.1503.017



TLB Application (Tractor | Loader | Bucket)

5- Auxiliary Functions Proportional Pilot Pressure Control Manifold . Extend-a-Hoe . Left & Rigth Stabilizer . Accessory implement . 2x Reverse Criss-Cross Flow Pattern Control







Hydraulic Diagram

Electronic Controls



Multi-Function Joystick Controller with FRP Proportional Rollers



proportional control levers and microprocessor-based MMS (Machine Management System)

Finger-tip



TLB-Tractor/Loader / Bucket

TLB's (Tractor | Loader | Bucket) in action:



In-cabin Controls



TECNORD FIELD OF EXPERTISE: Electro-Hydraulics and Electronics for:

EDGE CUTTERS AND MOWERS



Dual Path | 4-function Proportional Valve System Mod. 15.1304.106

. Typical Input Flow: **50 It/min** . Max. Work Pressure: 250 bar . Load-holding valves on REACH and LIFT . FLOAT on HEAD ANGLE



Electronic Controls









Tractor-mounted Edge Cutters in action



SALT SPREADERS AND SNOW PLOWS

P/N 15.2104.016



3- Proportional Functions Electro-Hydraulic Control Block

> - Conveyor (Auger) - Spinner - Water moisturing



Hydraulic Diagram

Electronic Controls



IN-CABIN CONTROL BOX .Microprocessor-based unit with Multi-Programmable functions .Input / Output connections to valves and accessories



Conveyor | Auger **RPM** sensor



GPS / GPRS GSM Unit









Truck-mounted Salt Spreader Systems and Snow Plows in action:

ROUGH TERRAIN TELEHANDLERS

Mod. HDS34 Flow Sharing Valves with MLT/FD5 Closed Loop **Proportional Controls**



Mod. HDS20 Open Center Valve with MPP/T043 Open Loop **Proportional Actuators**

Mod. HDS30 Load Sensing Valve

with MLT/FD5 Closed Loop

Proportional Actuators



CASE-New Holland



Merlo





MMS Machine Management System with CAN-bus Communications Network

HDS34 - Hydraulic Diagram





In-cab Joystick



Aerial Basket Boom Extension and Angle Sensor Radio Remote Control



Machine Management System Units



FARESIN Industries





GENIE by Terex

Manitou







Bobcat-Doosan





TECNORD STANDARD PRODUCT LINE:

MLT/FD5 CLOSED-LOOP PROPORTIONAL ACTUATORS



Mounting Style "A": Direct Flange Mounting



Mounting Style "B": Adapter Flange Mounting



Mounting Style "C": Double-Acting Servo-Piston



Functions:

The MLT-FD5 / D electro-hydraulic proportional actuator has been designed to shift a directional control valve spool either directly (FL version) or by means of a servo-piston mechanically connected to it (SP version)

The internal closed loop position control configuration of Mod. MLT-FD5-D makes the valve spool achieve the desired position with accuracy levels approaching the performance of a servo-valve, by continuously comparing the set-point of a remote control device (Potentiometer, Joystick, Machine Management System) with the feed-back signal generated by a high-precision Hall effect position transducer.

Features :

. Two independent proportional valves

- Control configuration: bidirectional with MOTOR SPOOL center position for fail-safe return to neutral in case of power loss
- Flow rate: 0.2 to 0.5 lt/min max. flow requirement under normal control conditions
- Work pressure: 12 to 35 bar

Hall effect / Contactless spool position sensor

- Excellent linear control on 100% of spool travel
- 8.5 mm standard control stroke from each side of NEUTRAL / 13.5 mm for FLOAT position in one direction only
- No "cross talking" between adjacent work sections

Built-in Electronics

- ANALOG OPERATING MODE: +5Volts supply to external potentiometers or joystick controllers
- CAN BUS OPERATING MODE: the remote control set point is processed via CAN bus according to ISO 11898 at 250 Kbit/s by means of address-based (SAE J1939) or message-based (CAN2.0B) protocols

APPLICATIONS

- High performance proportional control of stackable or monoblock directional control valves
- Proportional control of varaible displacement pumps and motors
- Engine governor RPM controls

Typical Control Configuration of a 2-Sections Proportional Valve by means of a Dual-Axes Joystick Controller







Application Examples:

Mounting Style "A": TECNORD Mod. TDV100



Mounting Style "B": **Bucher HDS34**



Mounting Style "C": BOSCH-REXROTH Mod. SX14

.... because Power is nothing without Control

TECNORD STANDARD PRODUCT LINE

TDV- Tecnord Directional Valves





Multi-function Proportional Valve System Mod. SF1202-CSB for 2-Ton Electrical Fork Lift Truck

> . Typical Input Flow: 80 It/min . Max. Work Pressure: 280 bar . Load-holding valves on TILT and AUX. functions



Hydraulic Diagram



Electric Side-Shifter



Diesel Fork Lift



Commissioner

FORK LIFT TRUCKS









Tecnord-Modena / Italy

Staker

P|**N** 15.1302.193

Electro-Hydraulic Control System for Self-Propelled | Crawler-type **Aerial Platform**









Electronic Controls



Base Control Box for Self-Propelled **Aerial Platform**



Typical Input Flow : Max. Work Pressure:

Joystick Controllers Fingertip levers Multi-function Grips

MMS - Machine **Management Systems**



30 It/min

250 bar

dual-path proportional control circuit

Aerial Basket Radio Remote Control



2-axes **Proportional** Inclinometer

AERIAL PLATFORMS

Self-Propelled Craler-type Aerial Platform



Self-Propelled Articulated Aerial Platform

Self-Propelled Scissor Lift

Electro-Hydraulic Valve System for:

CVT (Continuously Variable Transmissions)

P/N 15.1503.048



Pressure (bar) vs. PWM Current (mA) diagram for quick fill-up and soft engagement of a wet-disc clutch





8 - Proportional Pressure Reducing Valves Manifold Block for CVT Transmissions



Mod. IP-PRZ-T059 **Proportional Pressure Reducing Valve**

Typical Clutch Cycle: 2.

ramp

- Preliminary "quick fill-up" phase at top current until pressure begins to raise within the cluctch piston chamber
- Modulated Current ramp to generate a "soft engagement" of clucth discs









NEW HOLLAND T7000 Series

MAGNUM Series

Steyr Mod. 6255 CVT

TECNORD STANDARD PRODUCT LINE

Tecnord Directional Valve Mod. TDV100



Vehicles with Stabilizers



TECNORD FIELD OF EXPERTISE: Electro-Hydraulics and Electronics for:

LIFT & LOWER CONTROLS

	Ramp-up from 0 to max. speed
	Riding at max. speed
	Ramp-down from max. speed to creep speed
	Coasting to a stop at creep speed.

	Ramp-up from 0 to max. speed
	Riding at max. speed
	Ramp-down from max. speed to creep speed
	Coasting to a stop at creep speed.

TECNORD FIELD OF EXPERTISE:

Electro-Hydraulics and Electronics for:

Electronic Compensation's scope:

To eliminate the PRESSURE COMPENSATOR SPOOL on stackable valves and to provide pressure compensation under variable load conditions by varying the opening of the DIRECTIONAL CONTROL SPOOL in response to the variation of LOAD SENSING SIGNALS sensed by means of pressure transducers and a microprocessor-based control logic.

Proportional actuator MLT-FD5/1 with Pressure Transducer TP1

tional control valve

The elimination of PRESSURE COMPENSATOR SPOOLS means:

(1) Control Joystick

energy saving (thanks to the limination of the delta-p across the spool itself) reduced sized of directional spool valves

- possibility to change the control mode of a given hydraulic function by switching from an electronic configuration to another, such as:

. LOAD SENSING . FLOW SHARING

. ANTI-SATURATION

. ANTI-STALL . HORSE-POWER LIMITER

Rotale the JOYSTICK LEVER by 18 ° along the Y-Y axis to generate a 3.5 Volt signal to the PROPORTIONAL ACTUATOR 1 1.

Microprocessor based electronic controlle

In response to a 3.5 V input signal, the PROPORTIONAL ACTUATOR will generate a 4.67 mm STROKE OF THE DIRECTIONAL SPOOL 2.

For a given CONTROL SPOOL PROFILE, let us assume that a 4.67 mm stroke generates a 9 lt/min flow under "15 bar pump pressure", whereas З. 15 bar is the typical "stand-by pressure" of a Closed Center Load Sensing System This condition is represented by the BLUE dotted line on the graph of Fig. 4

Let us assume that the JOYSTICK LEVER is rotated along the X-X to activate the PROPORTIONAL ACTUATOR 2 connected to 4 the DIRECTIONAL VALVE 2 and that in response to this command, a load-induced pressure of 45 bar is created in the circuit. The Load Sensing circuit built into the valve system, will then urge the pump to build up (45+15)=60 bar pressure

- 5. Being the DIRECTIONAL VALVE SECTION 1 non-pressure compensated, if the SPOOL STROKE is still 4.67 mm, the 9 lt/min flow rate will increase by a significant amount corresponding to the square root of the delta-p variation from 15 to 60 bar (Bernoulli's law)
- 6. Conversely, if the system were equipped with means of measuring the delta-p variations, then it would be possible to modify the DIRECTIONAL VALVE SPOOL STROKE to maintain the desired 9 lt/min imposed by the "18 ° rotation angle of the joystick", that, in the end is the most intuitive reference point for the Machine Operator.
- The required control system needed to accomplish the above modification of working parameters, should work as follows: 7. - Read the instant pressure surge from 15 to 60 bar
 - Calculate the SPOOL STROKE reduction neeed to maintain 9 lt/min under a 60 bar delta-p according to the Bernoulli's law algorithm
 - Establish the correct correlation between the calculated SPOOL STROKE and the Vin (input signal) needed to produce it by means of the control logic of the MLT-FD5/1 actuator.
- As a result of the ELECTRONIC COMPENSATION, the control characteristic shall shift from the curve Q15 b (Blue) 8. to the curve Q60 (Magenta)

4 - Data-base acquisition process

Data acquisition process

The flow metering characteristic of a directional spool designed for ELECTRONIC PRESSURE COMPENSATION must be tested to determine the different FLOW (lt/min) vs STROKE (mm) characteristic under varying DELTA- PRESSURE (bar) conditions (Fig. 5)

carried out to trace a set of (Delta-P vs. FLOW) curves. of (Delta P vs. Flow) curves

Performance Level / Example 1

The black / ragged horizontal line on the graph of Fig. 9 is the flow of a directional spool set for 35 lt/min under 40 bar load induced pressure

FLOW (It/min) and PRESSURE (bar)

is about 100 ms.

Electronic Pressure Compensation

To attain the graph of Fig. 5 (FLOW vs. STROKE), a data acquisition process has to be

A step / linear motor is used to increase the spool stroke by 1/10 mm at a time, while a PROPORTIONAL FLOW REGULATOR creates a variable flow across the orifice and consequently a variable DELTA-P that has to be recorded and then plotted into the set

By plotting the acquired data-base by means of proper mathematical algorithms, it is now

If an instant peak pressure of 100 bar is applied, the transition time between the moment t the pressure peak is sensed and the moment the spool retracts to maintain the preset flow rate,